- 11. Show that the set $S = \{(x, y, z) \in \mathbb{R}^3; z = x^2 y^2\}$ is a regular surface and check that parts a and b are parametrizations for *S*:
 - **a.** $\mathbf{x}(u, v) = (u + v, u v, 4uv), (u, v) \in \mathbb{R}^2$.
 - ***b.** $\mathbf{x}(u, v) = (u \cosh v, u \sinh v, u^2), (u, v) \in \mathbb{R}^2, u \neq 0.$

Which parts of *S* do these parametrizations cover?

12. Show that **x**: $U \subset R^2 \to R^3$ given by

$$\mathbf{x}(u, v) = (a \sin u \cos v, b \sin u \sin v, c \cos u), \quad a, b, c \neq 0,$$

where $0 < u < \pi$, $0 < v < 2\pi$, is a parametrization for the ellipsoid

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1.$$

Describe geometrically the curves u = const. on the ellipsoid.

- *13. Find a parametrization for the hyperboloid of two sheets $\{(x, y, z) \in \mathbb{R}^3; -x^2 y^2 + z^2 = 1\}$.
 - 14. A half-line $[0, \infty)$ is perpendicular to a line *E* and rotates about *E* from a given initial position while its origin 0 moves along *E*. The movement is such that when $[0, \infty)$ has rotated through an angle θ , the origin is at a distance $d = \sin^2(\theta/2)$ from its initial position on *E*. Verify that by removing the line *E* from the image of the rotating line we obtain a regular surface. If the movement were such that $d = \sin(\theta/2)$, what else would need to be excluded to have a regular surface?
- *15. Let two points p(t) and q(t) move with the same speed, p starting from (0, 0, 0) and moving along the z axis and q starting at (a, 0, 0), $a \neq 0$, and moving parallel to the y axis. Show that the line through p(t) and q(t) describes a set in R^3 given by y(x a) + zx = 0. Is this a regular surface?
 - 16. One way to define a system of coordinates for the sphere S², given by x² + y² + (z − 1)² = 1, is to consider the so-called *stereographic projection* π: S² ~ {N} → R² which carries a point p = (x, y, z) of the sphere S² minus the north pole N = (0, 0, 2) onto the intersection of the *xy* plane with the straight line which connects N to p (Fig. 2-12). Let (u, v) = π(x, y, z), where (x, y, z) ∈ S² ~ {N} and (u, v) ∈ xy plane.

a. Show that π^{-1} : $R^2 \to S^2$ is given by

$$\pi^{-1} \begin{cases} x = \frac{4u}{u^2 + v^2 + 4}, \\ y = \frac{4v}{u^2 + v^2 + 4}, \\ z = \frac{2(u^2 + v^2)}{u^2 + v^2 + 4}. \end{cases}$$