

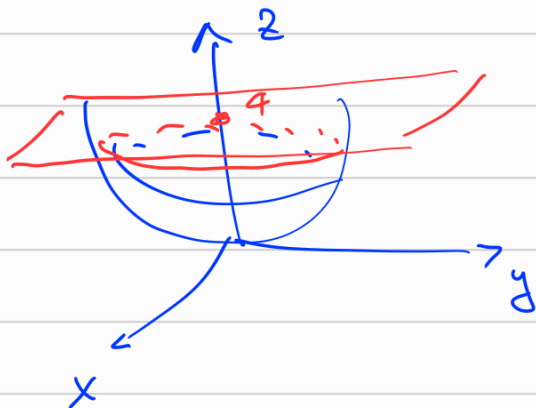
Esercizio 4.24 Abate Tavana

(1)

p. 222

$$S \subseteq \mathbb{R}^3 \quad S = \{z = x^2 + y^2\}$$

paraboloide di rotazione



(i) calcolare K

(ii) direzioni principali nei punti della curva

$$\sigma: \mathbb{R} \rightarrow S$$

$$\sigma(t) = (2 \cos t, 2 \sin t, 4)$$

direzioni principali di curvatura = autovettori di $-dN_p$

$$-dN_p = I_p^{-1} \cdot \overline{II}_p$$

$$\underline{x}(u, v) = (u, v, u^2 + v^2) \quad \text{come grafico}$$

$$\underline{x}_u = (1, 0, 2u) \quad \underline{x}_u \wedge \underline{x}_v = (-2u, -2v, 1)$$

$$\underline{x}_v = (0, 1, 2v)$$

$$E = \underline{x}_u \cdot \underline{x}_u = 1 + 4u^2$$

$$F = 4uv$$

$$G = 1 + 4v^2$$

$$I_p = \begin{bmatrix} 1 + 4u^2 & 4uv \\ 4uv & 1 + 4v^2 \end{bmatrix}$$

$$\underline{x}_{uu} = (0, 0, 2) \quad \underline{x}_{uv} = (0, 0, 0) \quad \underline{x}_{vv} = (0, 0, 2)$$

$$\|\underline{x}_u \wedge \underline{x}_v\| = \sqrt{1 + 4u^2 + 4v^2} = \sqrt{E_G - F^2} \quad (2)$$

$$N = \frac{1}{\sqrt{\quad}} (-2u, -2v, 1)$$

$$e = \frac{2}{\sqrt{\quad}}, \quad f = 0, \quad g = \frac{2}{\sqrt{\quad}}$$

$$II_P = \frac{1}{\sqrt{\quad}} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

$$K \rightarrow \text{immediato} = \frac{eg - f^2}{E_G - F^2} = \dots$$

$$-dN_P = I_P^{-1} \cdot II_P$$

$$\mathbb{R} \xrightarrow{\quad} \mathbb{R}^2 = U \xrightarrow{\underline{x}} S$$

$$\left[\begin{array}{l} t \rightarrow (2\cos t, 2\sin t) \\ (u, v) \rightarrow (u, v, \sqrt{u^2 + v^2}) \end{array} \right]$$

$$\underline{\sigma} = (2\cos t, 2\sin t, 4)$$

$$\begin{cases} u = 2\cos t \\ v = 2\sin t \end{cases} \quad \text{in questi punti:}$$

$$I_P = \begin{bmatrix} 1 + 16\cos^2 t & 16\cos t \sin t \\ 16\cos t \sin t & 1 + 16\sin^2 t \end{bmatrix}$$

$$\det I_p = EG - F^2 = 1 + 16 \cos^2 t + 16 \sin^2 t$$

$$= 17$$

(3)

$$I_p^{-1} = \frac{1}{17} \begin{bmatrix} 1 + 16 \sin^2 t & -16 \cos t \sin t \\ -16 \cos t \sin t & 1 + 16 \cos^2 t \end{bmatrix}$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$II_p = \frac{1}{\sqrt{17}} \cdot \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \frac{2}{\sqrt{17}} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$-dN_p = \frac{2}{17 \cdot \sqrt{17}} \begin{bmatrix} 1 + 16 \sin^2 t & -16 \sin t \cos t \\ -16 \sin t \cos t & 1 + 16 \cos^2 t \end{bmatrix}$$

autovettori??

$$\det \begin{bmatrix} (1 + 16 \sin^2 t) - \lambda & -16 \sin t \cos t \\ -16 \sin t \cos t & (1 + 16 \cos^2 t) - \lambda \end{bmatrix}$$

$$= (1 + 16 \sin^2 t)(1 + 16 \cos^2 t) - \lambda \left[1 + 16 \cos^2 t + 1 + 16 \sin^2 t \right]$$

$$+ \lambda^2 - 16 \cdot 16 \sin^2 t \cos^2 t$$

$$= \lambda^2 - \left[2 + \overset{16}{16\cos^2 t + 16\sin^2 t} \right] + \left(1 + \overset{16}{16\cos^2 t + 16\sin^2 t} \right) = 0 \quad (4)$$

$$\boxed{\lambda^2 - 18\lambda + 17 = 0}$$

$$(\lambda - 1)(\lambda - 17) = 0$$

$$\boxed{\lambda = 1, 17}$$

$$-dN_P = \frac{2}{17 \cdot \sqrt{17}} \begin{bmatrix} 1 + 16\sin^2 t & -16\sin t \cos t \\ -16\sin t \cos t & 1 + 16\cos^2 t \end{bmatrix}$$

act vel $\lambda = 1$

$$\frac{32}{17 \cdot \sqrt{17}} \begin{bmatrix} \sin^2 t & -\sin t \cos t \\ -\sin t \cos t & \cos^2 t \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\sin^2 t \cdot x - \sin t \cos t \cdot y = 0$$

$$\sin t \left[\sin t \cdot x - \cos t \cdot y \right] = 0$$

$$t \neq 0 \rightarrow \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \cos t \\ \sin t \end{bmatrix}$$

diraz. principale: $\cos t \cdot \underline{x}_u + \sin t \cdot \underline{x}_v$

$$\begin{bmatrix} \cancel{1} + 16 \sin^2 t & \cancel{-17} - 16 & -16 \sin t \cos t \\ -16 \sin t \cos t & \cancel{1} + 16 \cos^2 t & \cancel{-17} - 16 \end{bmatrix} \quad (5)$$

$$= 16 \begin{bmatrix} \sin^2 t - 1 & -\sin t \cos t \\ -\sin t \cos t & \cos^2 t - 1 \end{bmatrix}$$

$$= -16 \begin{bmatrix} \cos^2 t & \sin t \cos t \\ \sin t \cos t & \sin^2 t \end{bmatrix}$$

.....

— 0 —

Compito giugno 2017, Ex 1

$\sigma: I \rightarrow \mathbb{R}^3$ biinvoluzione

$\sigma(I) \subseteq$ sfera di raggio $R > 0$

$K: I \rightarrow \mathbb{R}$ curvatura di σ

Allora: $K(t) \geq 1/R \quad \forall t$



• possiamo supporre

$$S: x^2 + y^2 + z^2 = R^2$$

(cioè centro nell'origine)

• $\alpha: I \rightarrow S$ parametrizzazione
 $\alpha(s) = (x(s), y(s), z(s))$

Ipoteză: $\alpha(I) \subseteq S$

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cică: $\alpha(s) \cdot \alpha(s) \equiv R^2$

derivăm:

$$2 \alpha(s) \cdot \alpha'(s) \equiv 0$$

cică: $\alpha(s) \perp \underline{t}(s)$

derivăm ancora:

$$\alpha'(s) \cdot \alpha'(s) + \alpha(s) \cdot \alpha''(s) \equiv 0$$

$$1 + (\alpha(s) \cdot \underline{n}(s)) \kappa(s) \equiv 0$$

$$\kappa(s) = - \frac{1}{\alpha(s) \cdot \underline{n}(s)}$$

$$|\alpha(s) \cdot \underline{n}(s)| \leq \|\alpha(s)\| \cdot \|\underline{n}(s)\| = \|\alpha(s)\| = R$$

poind că $\kappa > 0$ prin curbură,

deve essere $\alpha(s) \cdot \underline{n}(s) < 0$

$$\rightarrow \kappa = \left| - \frac{1}{\alpha(s) \cdot \underline{n}(s)} \right| = \frac{1}{|\alpha(s) \cdot \underline{n}(s)|} \leq R$$

$$\Rightarrow \kappa \geq \frac{1}{R}$$

Sapendo la teoria delle superfici

(7)

$$k_n = k(\underline{n}, \underline{N})$$



$$\Rightarrow |k_n| \leq k$$

$k_n =$ curv. normale
di C in P

però: ① k_n dipende non da C
ma solo dalla direzione \underline{n}

$$\textcircled{2} k_1 \leq k_n \leq k_2$$

curvature principali

Adesso: • $k \geq |k_n|$

• su una sfera $k_n = \underline{\underline{1/R}}$
ogni punto per cui $k_1 = k_2 = 1/R$

→ • fine dell'esercizio •

Giugno 2018, Ex 2

(8)

$$S = \{x^4 + y^4 + z^4 = 1\}$$

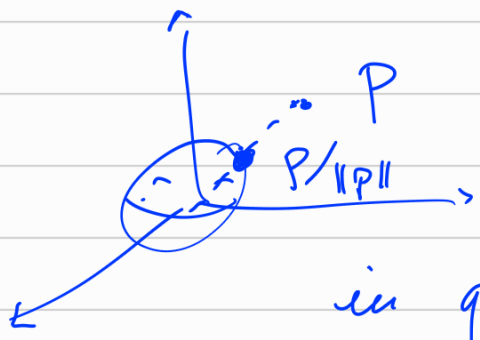
① S è reg e orientabile

② $F: S \rightarrow S^2$ (sfera unitaria)

$$P \rightarrow \frac{P}{\|P\|}$$

F è differenzabile

• F è C^∞ perché è la restrizione di una funz. C^∞ su $\mathbb{R}^3 \setminus \{0\}$ e $S \subseteq \mathbb{R}^3 \setminus \{0\}$

•  P
 $P/\|P\|$
in quanti punti incontra S ?

$$r: (tx_0, ty_0, tz_0) \quad t > 0$$

$$r \cap S \quad t^4 (x_0^4 + y_0^4 + z_0^4) = 1$$

$$t^4 = \frac{1}{(\quad)} \quad t = \pm \sqrt{(\quad)}$$

una sola radice positiva -

③ S è compatta + connessa

⑨

orientata, orientata alla sfera

$K : S \rightarrow \mathbb{R}$ curvatura gaussiana di S

$$\int_S K \, dA = ?? = 4\pi$$

Teorema di Gauss-Bonnet

S connessa, compatta, orientabile

allora:

$$\int_S K \, dA = 2\pi \cdot \chi(S)$$

esempio: per $S = S^2$, $K \equiv 1/R^2$

$$\int_S \frac{1}{R^2} \, dA = \frac{1}{R^2} \cdot \text{area}(S)$$

$$= \frac{1}{R^2} \cdot 4\pi R^2 = \underline{\underline{4\pi}}$$

$$\sigma: \mathbb{R} \rightarrow \mathbb{R}^3$$

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$$\sigma(t) = g(t) \cdot (\cos t, \sin t, 0)$$

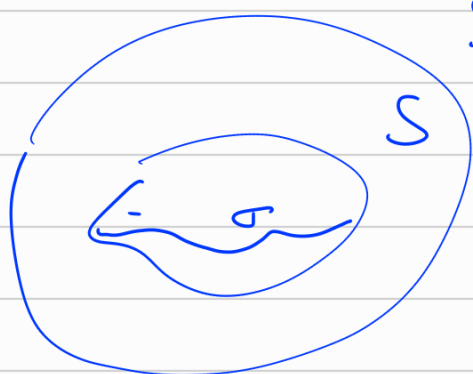
$$g(t) = \frac{1}{\sqrt{\cos^4 t + \sin^4 t}}$$

$\sigma = \text{Curve in } \mathbb{R}^3$

• $\sigma(\mathbb{R}) \subseteq S$ sub $x^4 + y^4 + z^4 = 1$

• $\|\sigma'(\pi/4)\|$

• $\|(F\sigma)'(\pi/4)\|$



S^2

$F\sigma$



S^2

$$\sigma(t) = g(t) \cdot (\cos t, \sin t, 0)$$

$$\sigma'(t) = \left(\cos t \cdot g'(t) - g(t) \cdot \sin t, \right.$$

$$\left. \sin t \cdot g'(t) + g(t) \cos t, 0 \right)$$

$$g'(t) = -\frac{1}{4} (\cos^4 t + \sin^4 t)^{-5/4} \cdot (-4 \cos^3 t \sin t + 4 \sin^3 t \cos t)$$

$$g'(\pi/4) =$$

(11)

$$\cos \pi/4 = \sin \pi/4 = \frac{\sqrt{2}}{2} \quad ()^2 = \frac{1}{2}, \quad ()^4 = \frac{1}{4}$$

$$g'(\pi/4) = -\frac{1}{4} \left(\frac{1}{4} + \frac{1}{4} \right)^{-5/4} \cdot 0 = 0$$

$$g(\pi/4) = \left(\frac{1}{4} + \frac{1}{4} \right)^{-1/4} = \left(\frac{1}{2} \right)^{-1/4} = 2^{1/4} = \sqrt[4]{2}$$

$$\sigma'(\pi/4) = \sqrt[4]{2} \left(-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0 \right)$$

$$= g(\pi/4) \underbrace{\left(-\sin \pi/4, \cos \pi/4, 0 \right)}_{\| \| = 1}$$

$$\| \sigma'(\pi/4) \| = \sqrt[4]{2}$$

$$\sigma(t) = g(t) \cdot (\cos t, \sin t, 0)$$

$$(F_{\circ} \sigma)(t) = \frac{\sigma(t)}{\| \sigma(t) \|} = (\cos t, \sin t, 0)$$

$$(F_{\circ} \sigma)'(t) = (-\sin t, \cos t, 0)$$

$$\| (F_{\circ} \sigma)'(\pi/4) \| = 1$$

$$S \text{ sup data } \{z = 1 - x^2 - y^2\} \quad (12)$$

orientare S in modo che $\underline{N}_{(0,0,1)} = (0,0,1)$
Punto vettore

$S \rightarrow$ cubo, oppure catena
cine devo parametrizzarla

$$\underline{X} : \mathbb{R}^2 \rightarrow S \subseteq \mathbb{R}^3$$

$$(u, v) \mapsto (u, v, 1 - u^2 - v^2)$$

\underline{X} dà un'orientazione. È quella voluta?

basta calcolare $N = \frac{\underline{X}_u \wedge \underline{X}_v}{\|\underline{X}_u \wedge \underline{X}_v\|}$

e confrontarlo con quello assegnato

$$\underline{X}_u = (1, 0, -2u), \quad \underline{X}_v = (0, 1, -2v)$$
$$\underline{X}_u \wedge \underline{X}_v = (2u, 2v, 1)$$

in $P = (0, 0, 1)$ deve essere $(u, v) = (0, 0)$

$$\underline{X}_u \wedge \underline{X}_v = (0, 0, 1) \quad \underline{OK}$$

Sulle dispense, esercizio 3.11, pag 275