

Giugno 2019, ex. 4

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$\mu \mathbb{R}^4$ (x_1, x_2, x_3, x_4)

$$\omega = x_3 x_4 dx_1 \wedge dx_2 + x_2 x_4 dx_1 \wedge dx_3 + x_2 x_3 dx_1 \wedge dx_4$$

- Calcolare: $d\omega$, $*\omega$, $d(*\omega)$, $\omega \wedge *\omega$
- Trovare, se esiste η : $\omega = d\eta$

$$\begin{aligned} d\omega &= d(x_3 x_4) \wedge dx_1 \wedge dx_2 \\ &\quad + d(x_2 x_4) \wedge dx_1 \wedge dx_3 \\ &\quad + d(x_2 x_3) \wedge dx_1 \wedge dx_4 \end{aligned}$$

$$\begin{aligned} &= [x_4 dx_3 + x_3 dx_4] \wedge dx_1 \wedge dx_2 \\ &\quad + [x_4 dx_2 + x_2 dx_4] \wedge dx_1 \wedge dx_3 \\ &\quad + [x_3 dx_2 + x_2 dx_3] \wedge dx_1 \wedge dx_4 \end{aligned}$$

$$\begin{aligned} &= x_4 \underbrace{dx_1 \wedge dx_2 \wedge dx_3} + x_3 \underbrace{dx_1 \wedge dx_2 \wedge dx_4} \\ &\quad - x_4 \underbrace{dx_1 \wedge dx_2 \wedge dx_3} + x_2 \underbrace{dx_1 \wedge dx_3 \wedge dx_4} \\ &\quad - x_3 \underbrace{dx_1 \wedge dx_2 \wedge dx_4} - x_2 \underbrace{dx_1 \wedge dx_3 \wedge dx_4} \\ &= 0 \quad (\omega \text{ è chiusa}) \end{aligned}$$

$$* \omega = * (x_3 x_4 dx_1 \wedge dx_2 + x_2 x_4 dx_1 \wedge dx_3 + x_2 x_3 dx_1 \wedge dx_4) \quad (2)$$

$$*(dx_1 \wedge dx_2) = + dx_3 \wedge dx_4 \quad \cdot$$

$$*(dx_1 \wedge dx_3) = - dx_2 \wedge dx_4 \quad \cdot \cdot$$

$$*(dx_1 \wedge dx_4) = + dx_2 \wedge dx_3 \quad \dots$$

$$\cdot \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 3 & 4 \end{pmatrix} \rightarrow +$$

$$\cdot \cdot \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & 3 & 2 & 4 \end{pmatrix} = (23) \rightarrow -$$

$$\dots \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & 4 & 2 & 3 \end{pmatrix} = (243) \rightarrow +$$

$$* \omega = \underline{x_3 x_4} \underline{dx_3} \wedge \underline{dx_4} - \underline{x_2 x_4} \underline{dx_2} \wedge \underline{dx_4} + \underline{x_2 x_3} \underline{dx_2} \wedge \underline{dx_3}$$

• $d(*\omega) = 0$ ogni termine ha un dx_i ripetuto.

$$\omega \wedge (*\omega) =$$

$$\begin{aligned} & \left[\underline{x_3 x_4} dx_1 \wedge dx_2 + \underline{x_2 x_4} dx_1 \wedge dx_3 + \underline{x_2 x_3} dx_1 \wedge dx_4 \right] \wedge \\ & \left[\underline{x_3 x_4} \underline{dx_3} \wedge \underline{dx_4} - \underline{x_2 x_4} \underline{dx_2} \wedge \underline{dx_4} + \underline{x_2 x_3} \underline{dx_2} \wedge \underline{dx_3} \right] \\ & = \end{aligned}$$

$$(x_3 x_4)^2 dx_1 \wedge dx_2 \wedge dx_3 \wedge dx_4$$

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$$- (x_2 x_4)^2 dx_1 \wedge dx_3 \wedge dx_2 \wedge dx_4$$

$$+ (x_2 x_3)^2 dx_1 \wedge dx_4 \wedge dx_2 \wedge dx_3$$

$$= \left[(x_3 x_4)^2 + (x_2 x_4)^2 + (x_2 x_3)^2 \right] dx_1 \wedge dx_2 \wedge dx_3 \wedge dx_4$$

Osservazione: in \mathbb{R}^n $\omega = \sum a_I dx_I$

ω k -forma

$*\omega = (n-k)$ forma

$$*\omega = \sum (\pm) a_I dx_J$$

dove $I \cup J = \{1, 2, \dots, n\}$

$$* a_I dx_I = (-1)^{I+J} a_I dx_J$$

$$I+J =$$

$$= i_1 \dots i_k j_1 \dots j_{n-k}$$

$$a_I dx_I \wedge (* a_I dx_I) =$$

$$a_I^2 \cdot (-1)^{I+J} dx_I \wedge dx_J =$$

$$= \underbrace{(-1)^{I+J} \cdot (-1)^{I+J}}_{+1} a_I^2 dx_1 \wedge dx_2 \wedge \dots \wedge dx_n$$

quindi in generale:

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$$\omega = \sum_I a_I dx_I \quad k\text{-forma}$$

$$\omega \wedge (*\omega) = \left(\sum_I a_I^2 \right) dx_1 \wedge dx_2 \wedge \dots \wedge dx_n$$

• trovare η : $d\eta = \omega$

ω chiusa ($d\omega = 0$), \mathbb{R}^4 contrattibile

$\Rightarrow \omega$ esatta

trovare η = "integrare"

$$\omega = dx_1 \wedge \underbrace{(x_3 x_4 dx_2 + x_2 x_4 dx_3 + x_2 x_3 dx_4)}_{\psi}$$

$$\omega = dx_1 \wedge \psi$$

$$f \ a \rightarrow F \ a - \int F \ g$$

$$\eta = x_1 \psi - \int 0 = x_1 \psi$$

$$F = x_1, \quad g = d\psi = 0$$

$$\eta = x_1 x_3 x_4 dx_2 + x_1 x_2 x_4 dx_3 + x_1 x_2 x_3 dx_4$$

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in \mathbb{R}^n

$$\omega = \sum_{i=1}^n (-1)^i x_i dx_1 \wedge \dots \wedge \overset{\wedge}{dx_i} \wedge \dots \wedge dx_n$$

in $\mathbb{R}^2 = -x_1 dx_2 + x_2 dx_1$

in $\mathbb{R}^3 = -x_1 dx_2 \wedge dx_3 + x_2 dx_1 \wedge dx_3 - x_3 dx_1 \wedge dx_2$

Calculate $d\omega$, $\ast\omega$, $\omega \wedge (\ast\omega)$

$$d\omega = \sum_{i=1}^n (-1)^i \underbrace{dx_i \wedge dx_1 \wedge \dots \wedge \overset{\wedge}{dx_i} \wedge \dots \wedge dx_n}_{\text{terms cancel out}}$$

$$= \sum_{i=1}^n (-1)^i (-1)^{i-1} dx_1 \wedge \dots \wedge dx_n$$

$$= -n (dx_1 \wedge \dots \wedge dx_n)$$

$$\ast\omega: \ast (dx_1 \wedge \dots \wedge \overset{\wedge}{dx_i} \wedge \dots \wedge dx_n) = \pm dx_i$$

$$\sigma = \begin{pmatrix} 1 & 2 & \dots & i-1 & i & i+1 & \dots & n-1 & n \\ 1 & 2 & \dots & i-1 & i+1 & i+2 & \dots & n & i \end{pmatrix}$$

$$\sigma = (i \ i+1 \ \dots \ n)$$

σ è un ciclo di lunghezza $n-i+1$ (6)

$$\rightarrow (-1)^{n-i}$$

$$*w = \sum_{i=1}^n (-1)^i x_i (-1)^{n-i} dx_i$$

$$= \sum_{i=1}^n (-1)^n x_i dx_i$$

$$= \boxed{(-1)^n \cdot \sum_{i=1}^n x_i dx_i}$$

$$w \wedge (*w) = \left[\sum_{i=1}^n x_i^2 \right] dx_1 \wedge dx_2 \wedge \dots \wedge dx_n$$

$$dw = n\text{-forma} = (-n) \underbrace{dx_1 \wedge \dots \wedge dx_n}$$

$$w \wedge (*w) = n\text{-forma} =$$

$$\boxed{w \wedge (*w) = \left(-\frac{1}{n} \cdot \sum_{i=1}^n x_i^2 \right) dw}$$

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$\sigma: \mathbb{R} \rightarrow \mathbb{R}^2$ curva piana, nessun archio



$$d(P_0, r) = c$$

$r =$ retta tg a σ

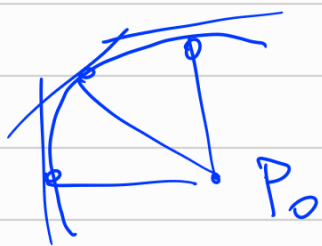
Allora: $\sigma =$ arco di circ. oppure segmento

σ $\cdot P_0$



$$r = \text{costante} = \sigma$$

σ :



$P_0 =$ centro di σ

distanza (centro, tg) = raggio
costante

$$\|a'(t) - P_0\|^2 = \text{costante}$$

$$\Rightarrow (\|a'(t) - P_0\|^2)' = 0$$

Quindi: $r =$ retta tangente

$$d(\text{retta}, \text{punto})^2 = \text{costante}$$

$$\sigma(s)$$

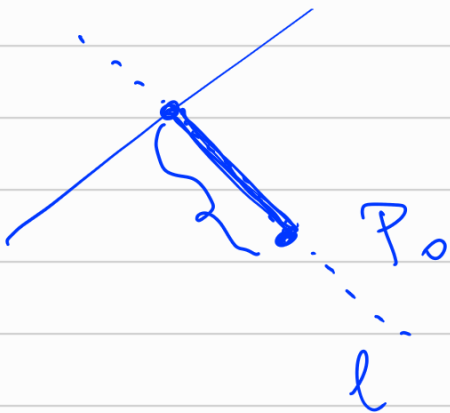
$$\sigma'(s) = \text{vettore } tg$$

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retta tg : $r: \sigma(s) + t\sigma'(s)$ = in forma parametrica



$$d(\text{retta}, \text{punto}) = ??$$



$$l: P_0 + u\sigma''(s)$$

$$r: \sigma(s) + t\sigma'(s)$$

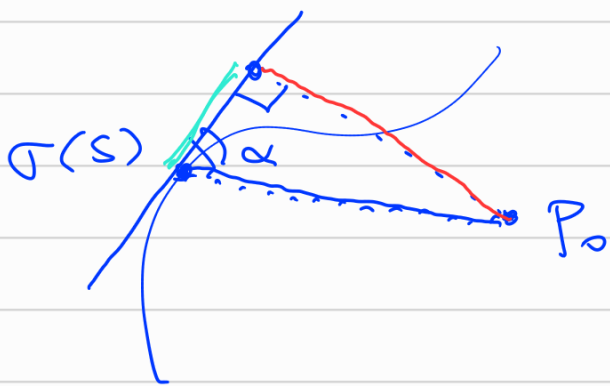
$$P_0 + u\sigma''(s) = \sigma(s) + t\sigma'(s)$$

$$\sigma(s) + \theta(s)\sigma'(s) = \text{proiett. ort. di } P_0 \text{ sulla } tg$$

$$\|(\sigma(s) - P_0) + \theta(s)\sigma'(s)\|^2 = \text{costante}$$

$$(\quad) \cdot (\quad)$$

$$(a \cdot a)' = 2a \cdot a'$$



retta tangente

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$$P_0 = (x_0, y_0)$$

z: $\sigma(s) + t\sigma'(s)$

$\sigma(s) - P_0 = \text{retta}$

trovo $\alpha = \text{angolo fra } (\sigma(s) - P_0) \text{ e } \underline{\underline{\sigma'(s)}}$

→ trovo la distanza e devo rispetto ad s

$$(\sigma(s) - P_0) \cdot \sigma'(s) = \|\sigma(s) - P_0\| \cdot \cos \alpha$$

→ si dovrebbe fare =

Altimenti:

z: $\sigma(s) + t\sigma'(s)$

l: $u \cdot \sigma''(s)$



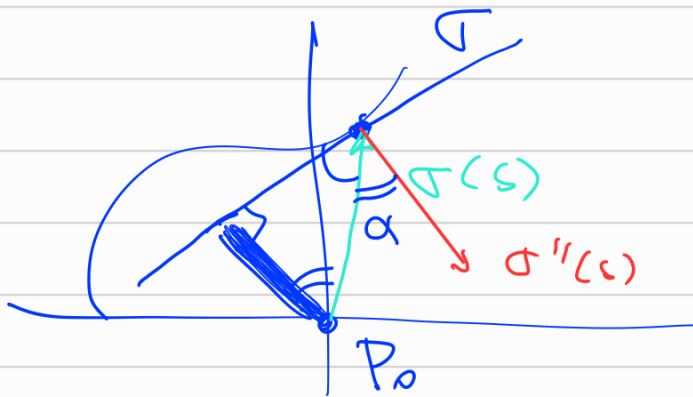
$$\sigma(s) + \underline{\underline{t}}\sigma'(s) = \underline{\underline{u}} \underline{\underline{h}}(s) \underline{\underline{n}}(s)$$

$$\sigma'(s) + t'\sigma' + t\sigma'' = u' \underline{\underline{h}}(s) \underline{\underline{n}}(s) + u \underline{\underline{h}}'(s) \underline{\underline{n}}(s) + u \underline{\underline{h}}(s) \underline{\underline{n}}'(s)$$

$$\underline{t} (1 + t') + t k \underline{n} = u' k \underline{n}$$

$$+ u k' \underline{n} - u k^2 \underline{t}$$

$$\underline{t} \left(\underbrace{1 + t' + u k^2}_{=0} \right) + \underline{n} \left(\underbrace{t k - u' k - u k'}_{=0} \right) = 0$$



$$\sigma(s) \cdot \sigma''(s)$$

$$b l u = \text{verde} \cdot \cos(\alpha)$$

$$\sigma(s) \cdot \sigma''(s) = \|\sigma(s)\| \cdot \|\sigma''(s)\| \cos \alpha$$

$$\cancel{\|\sigma(s)\|} \cdot \frac{\sigma(s) \cdot \sigma''(s)}{\cancel{\|\sigma(s)\|} \cdot \|\sigma''(s)\|} =$$

$$= \boxed{\frac{1}{k(s)} \cdot (\sigma(s) \cdot \sigma''(s))}$$

biangolo

= costante

$$\left(\sigma(s) \cdot \sigma''(s) \right)' = \sigma' \cdot \sigma'' \leftarrow 0$$

$$+ \sigma \cdot \sigma''' = 0$$

Distanza: $\sigma \cdot \underline{n}$

$$\begin{aligned} \sigma' \cdot \underline{n} + \sigma \cdot \underline{n}' &= \\ &= \sigma \cdot (-\underline{t}) = 0 \end{aligned}$$

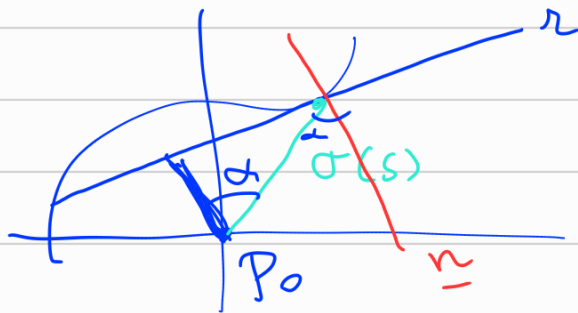
$C \equiv O$ curva
piana

$$\Rightarrow \sigma \perp \underline{t}$$

$$\underline{t} = \sigma' \Rightarrow \sigma \cdot \sigma' = 0$$

$$\Rightarrow (\sigma \cdot \sigma) = \underline{\underline{\text{costante}}}$$

Dell'angolo $P_0 = O$



$$d(\alpha, P_0) = \|\sigma(s)\| \cdot \cos \alpha$$

$$\sigma(s) \cdot \underline{n} = \|\sigma(s)\| \cdot \cos \alpha$$

$$\Rightarrow d(\alpha, P_0) = \|\sigma(s)\| \cdot \frac{\sigma(s) \cdot \underline{n}}{\|\sigma(s)\|}$$

$$= \sigma(s) \cdot \underline{n}$$

$$d(\underline{r}, P_0)' \equiv 0$$

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$$\sigma' \cdot \underline{n} + \sigma \cdot \underline{n}' =$$

$$= \cancel{\underline{t} \cdot \underline{n}} + \sigma \cdot (-k \underline{t} + e \cancel{\underline{e}})$$

$$= -k \cdot (\sigma \cdot \underline{t}) \equiv 0$$

$k \equiv 0 \rightarrow$ retta

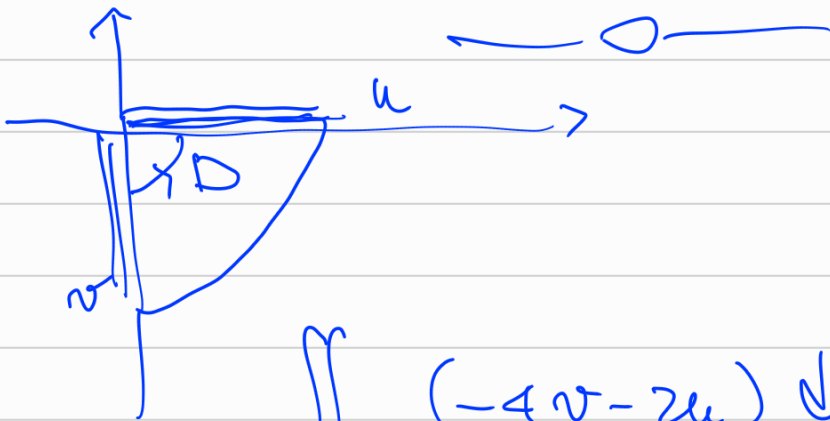
$k \neq 0$ su un intervallo $\&$ cui $k(s) \neq 0$

$$\rightarrow \sigma \cdot \underline{t} \equiv 0$$

$$\sigma \cdot \sigma' \equiv 0$$

integrando $(\sigma \cdot \sigma) = \text{costante}$

cioè: $\sigma =$ circonferenza di centro P_0



$$\iint_D (-4v - 2u) \, du \, dv$$

$$\int_D (-2u^2 + 2uv + v^2) \, du + \int_D (-2uv + 2v^2) \, dv$$